

Lecture Notes on

Forecasting

Yakov Ben-Haim

Former Yitzhak Moda'i Chair in Technology and Economics

Faculty of Mechanical Engineering

Technion — Israel Institute of Technology

Haifa 32000 Israel

yakov@technion.ac.il

<http://info-gap.com> <http://www.technion.ac.il/yakov>

Source material:¹

- Yakov Ben-Haim, 2010, *Info-Gap Economics: An Operational Introduction*, Chapter 6: Estimation and Forecasting, Palgrave-Macmillan.
- Yakov Ben-Haim, 2009, Info-gap forecasting and the advantage of sub-optimal models, *European Journal of Operational Research*, 197: 203–213. Link to pre-print at: <http://info-gap.com/content.php?id=22>

A Note to the Student: These lecture notes are not a substitute for the thorough study of books. These notes are no more than an aid in following the lectures.

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¹Additional material in the file: Yakov Ben-Haim, Lecture notes on info-gap estimation and forecasting, \lectures\risk\lectures\estim02.pdf.

1 1-D Dynamic System: European Central Bank Overnight Interest Rates

1.1 The Data and the Questions

Date	Interest rate	Implied λ
1 Jan 1999	4.50	
9 Apr 1999	3.50	0.778
5 Nov 1999	4.00	1.143
4 Feb 2000	4.25	1.063
17 Mar 2000	4.50	1.059
28 Apr 2000	4.75	1.056
9 Jun 2000	5.25	1.105
28 Jun 2000	5.25	1.000
1 Sep 2000	5.50	1.048
6 Oct 2000	5.75	1.045
11 May 2001	5.50	0.957
31 Aug 2001	5.25	0.955

Table 1: Interest rates for overnight loans at the European Central Bank (marginal lending facility). Source: <http://www.ecb.int/stats/monetary/rates/html/index.en.html>

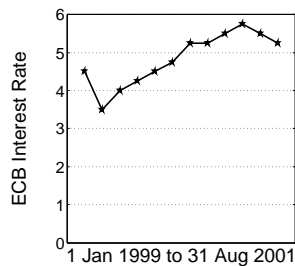


Figure 1: ECB Interest Rates

§ ECB overnight interest rates: table 1.

- First loans: 1999.
- Data through August 2001.
- 9 June 2000–31 August 2001: $\mu = 5.4\%$, $\sigma = 0.19\%$.
- Typical change: 25 basis points.
- Largest change: 100 basis points.

§ El-Qaeda attacks in US: 11 Sept 2001.

- **Predict next interest rate** on 9/12/2001, (1 day after 9/11).
- Asymmetric uncertainty: rate will go down (**Why?**), but **by how much?**

§ Questions:

- How to forecast the rate in light of the great uncertainty?
- How to assess confidence in the forecast?

1.2 1-Step Dynamics and Robustness

§ **Uncertain historical model** of dynamical variable y_n , e.g. interest rate:

$$y_1 = \lambda_1 y_0, \quad y_0 > 0, \text{ known, } \lambda_1 \text{ uncertain} \quad (1)$$

§ **Info-gap model. Asymmetric uncertainty:**

$$\mathcal{U}(h, \tilde{\lambda}) = \left\{ \lambda_1 : (1-h)\tilde{\lambda} \leq \lambda_1 \leq \tilde{\lambda} \right\}, \quad h \geq 0 \quad (2)$$

- $\tilde{\lambda}$: known and positive estimate transition coefficient.
- λ_1 : unknown true transition coefficient anticipated to be no greater, probably less, than $\tilde{\lambda}$.

§ **Slope-adjusted forecasting model.** We must choose the “slope” ℓ :

$$y_1^s = \ell y_0 \quad (3)$$

§ **Performance requirement:**

- Absolute error:

$$\varepsilon = |y_1^s - y_1| = |(\ell - \lambda_1)y_0| \quad (4)$$

- Performance requirement:

$$\varepsilon \leq \varepsilon_c \quad (5)$$

§ **Robustness:**

- Definition:

$$\hat{h}(\ell, \varepsilon_c) = \max \left\{ h : \left(\max_{\lambda_1 \in \mathcal{U}(h)} \varepsilon(\lambda_1) \right) \leq \varepsilon_c \right\} \quad (6)$$

- $m(h)$ is inner maximum in eq.(6): inverse of $\hat{h}(\varepsilon_c)$.
- **We will consider a special case:**

$$\ell \leq \tilde{\lambda} \quad (7)$$

- Recall: $y_0 > 0$ and known.
- $m(h)$ occurs for an extremal value of λ_1 at horizon of uncertainty h : either $\tilde{\lambda}$ or $(1-h)\tilde{\lambda}$.
- $m(h)$ is the greater of the following:

$$m_1(h) = |\tilde{\lambda} - \ell| y_0 \quad (8)$$

$$m_2(h) = |\ell - (1-h)\tilde{\lambda}| y_0 \quad (9)$$

- Clearly $m_1(h) > m_2(h)$ for **small** h because $\ell \leq \tilde{\lambda}$. To find the transition:

$$\tilde{\lambda} - \ell \geq \ell - (1-h)\tilde{\lambda} \quad (10)$$

$$\iff 2(\tilde{\lambda} - \ell) \geq h\tilde{\lambda} \quad (11)$$

$$\iff h \leq \frac{2(\tilde{\lambda} - \ell)}{\tilde{\lambda}} \quad (12)$$

- Hence:

$$m(h) = \begin{cases} (\tilde{\lambda} - \ell) y_0, & \text{if } h \leq \frac{2(\tilde{\lambda} - \ell)}{\tilde{\lambda}} \\ (\ell - (1-h)\tilde{\lambda}) y_0, & \text{else} \end{cases} \quad (13)$$

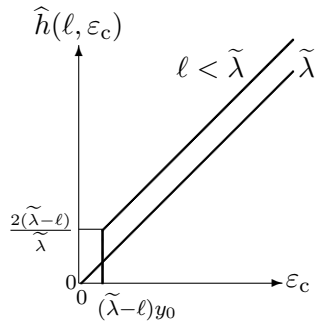


Figure 2: Robustness curve $\hat{h}(\ell, \varepsilon_c)$, eq.(14).

§ **Robustness function:** equate $m(h)$ to ε_c and solve for h to find the robustness. One finds (fig. 2):

$$\hat{h}(\ell, \varepsilon_c) = \begin{cases} 0, & \text{if } \varepsilon_c < (\tilde{\lambda} - \ell) y_0 \\ \frac{\varepsilon_c + (\tilde{\lambda} - \ell) y_0}{\tilde{\lambda} y_0}, & \text{else} \end{cases} \quad (14)$$

- Trade off: robustness \hat{h} up (good) as critical error ε_c up (not good).
- Zeroing: No robustness at estimated error.
- Discontinuous robustness curve for $\ell < \tilde{\lambda}$.
- Crossing robustness curves, fig. 3: preference reversal.

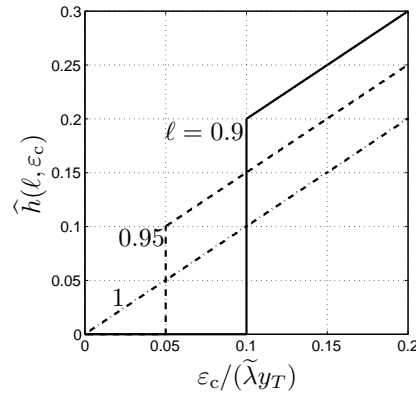


Figure 3: Robustness vs normalized forecast error. $\tilde{\lambda} = 1$, $y_T = 5.25$.

§ **Robustness curves for 3 slope-adjusted models, fig. 3:**

- $\ell = 1.0 \implies 0\%$ robustness at 0% error.
- $\ell = 0.95 \implies 10\%$ robustness at 5% error (more robust than $\ell = 1.0$).
- $\ell = 0.9 \implies 20\%$ robustness at 10% error (more robust than $\ell = 0.95$).

§ **Forecast:**

- Model used: $\ell = 0.9 \implies 20\%$ robustness at 10% error.
- Forecast: $y_{T+1}^s = 0.9y_T = 4.725$.
- Outcome:
 - $y_{T+1} = 4.75$ on 18.9.2001.
 - -0.5% forecast error.

1.3 Multi-Step Dynamics and Robustness

§ Uncertain historical model:

$$y_{t+1} = \lambda_{t+1}y_t, \quad t = 0, 1, 2, \dots, \quad y_0 > 0, \text{ known, } \lambda_{t+1} \text{ uncertain} \quad (15)$$

Thus:

$$y_t = y_0 \prod_{j=1}^t \lambda_j, \quad t = 1, 2, \dots \quad (16)$$

§ Info-gap model. Asymmetric uncertainty:

$$\mathcal{U}(h, \tilde{\lambda}) = \left\{ \lambda_t : (1-h)\tilde{\lambda} \leq \lambda_t \leq \tilde{\lambda}, \quad t = 1, 2, \dots \right\}, \quad h \geq 0 \quad (17)$$

Assume $\tilde{\lambda} > 0$.

§ Slope-adjusted forecasting model. We must choose the ‘slope’ ℓ :

$$y_{t+1}^s = \ell y_t^s \quad (18)$$

Thus:

$$y_t^s = \ell^t y_0 \quad (19)$$

§ Performance requirement:

- Absolute error:

$$\varepsilon_t = |y_t^s - y_t| = \left| \ell^t - \prod_{j=1}^t \lambda_j \right| y_0 \quad (20)$$

- Performance requirement:

$$\varepsilon_t \leq \varepsilon_c \quad (21)$$

§ Robustness:

- Definition:

$$\hat{h}_t(\ell, \varepsilon_c) = \max \left\{ h : \left(\max_{\lambda \in \mathcal{U}(h)} \varepsilon_t(\lambda) \right) \leq \varepsilon_c \right\} \quad (22)$$

- $m(h)$ is inner maximum in eq.(22): inverse of $\hat{h}_t(\varepsilon_c)$.

- **Special case:**

$$\ell \leq \tilde{\lambda} \quad (23)$$

- Recall: $y_0 > 0$.

• **If $h \leq 1$ then $m_t(h)$ occurs for extremal values of $\lambda_1, \dots, \lambda_t$ at horizon of uncertainty h :** all are either $\tilde{\lambda}$ or $(1-h)\tilde{\lambda}$.

- $m_t(h)$, for $h \leq 1$, is the greater of the following:

$$m_{t,1}(h) = \left(\tilde{\lambda}^t - \ell^t \right) y_0 \quad (24)$$

$$m_{t,2}(h) \geq \left| \ell^t - \prod_{j=1}^t (1-h)\tilde{\lambda} \right| y_0 \quad (25)$$

$$= \left| \ell^t - (1-h)^t \tilde{\lambda}^t \right| y_0 \quad (26)$$

- Clearly $m_{t,1}(h) > m_{t,2}(h)$ for small h . To find the transition:

$$\tilde{\lambda}^t - \ell^t \geq \ell^t - (1-h)^t \tilde{\lambda}^t \quad (27)$$

$$\Leftrightarrow \frac{\tilde{\lambda}^t - 2\ell^t}{\tilde{\lambda}^t} \geq -(1-h)^t \quad (28)$$

$$\Leftrightarrow (1-h)^t \geq \frac{2\ell^t - \tilde{\lambda}^t}{\tilde{\lambda}^t} \quad (29)$$

$$\Leftrightarrow 1-h \geq \left(\frac{2\ell^t - \tilde{\lambda}^t}{\tilde{\lambda}^t} \right)^{1/t} \quad (30)$$

$$h \leq 1 - \left(\frac{2\ell^t - \tilde{\lambda}^t}{\tilde{\lambda}^t} \right)^{1/t} \quad (31)$$

- Hence, for $h \leq 1$:

$$m_t(h) = \begin{cases} (\tilde{\lambda}^t - \ell^t) y_0, & \text{if } h \leq 1 - \underbrace{\left(\frac{2\ell^t - \tilde{\lambda}^t}{\tilde{\lambda}^t} \right)^{1/t}}_{h_s} \\ (\ell^t - (1-h)^t \tilde{\lambda}^t) y_0, & \text{if } h_s < h \leq 1 \end{cases} \quad (32)$$

which defines the constant, h_s , at which $m_t(h)$ switches.

- Equate $m_t(h)$ to ε_c and solve for h to find the robustness. One finds:

$$\hat{h}_t(\ell, \varepsilon_c) = \begin{cases} 0, & \text{if } \varepsilon_c < (\tilde{\lambda}^t - \ell^t) y_0 \\ 1 - \left(\frac{\ell^t y_0 - \varepsilon_c}{\tilde{\lambda}^t y_0} \right)^{1/t}, & \text{if } (\tilde{\lambda}^t - \ell^t) y_0 \leq \varepsilon_c \leq \ell^t y_0 \end{cases} \quad (33)$$

Note that eq.(33) is valid only for values of ε_c for which $\hat{h}_t \leq 1$.

- This robustness function, like eq.(14), p.4, shows:
 - Discontinuity.
 - Curve-crossing with $\hat{h}_t(\tilde{\lambda}, \varepsilon)$.

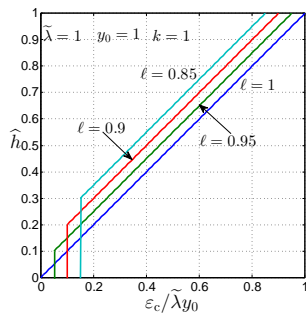


Figure 4: Robustness curves, eq.(33), $t = 1$.

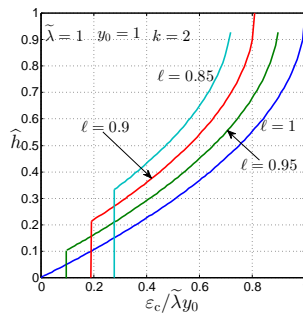


Figure 5: Robustness curves, eq.(33), $t = 2$.

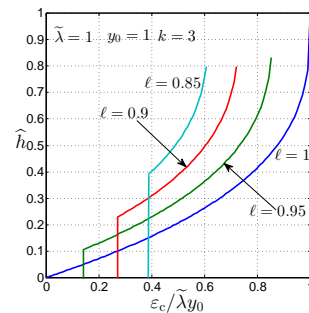


Figure 6: Robustness curves, eq.(33), $t = 3$.

§ Results: figs. 4–6:

- Curve crossing.

- Discontinuity of robustness curve occurs at larger ε_c for longer forecast (higher t .)
- Robustness curves shift right (bad) and fall (bad) as t increases. E.g.:

$$\hat{h}_{t=3}(\varepsilon_c = 0.4, \ell = 0.85) = 0.4 < \hat{h}_{t=2}(\varepsilon_c = 0.4, \ell = 0.85) = 0.43 < \hat{h}_{t=1}(\varepsilon_c = 0.4, \ell = 0.85) = 0.55 \quad (34)$$

- Cost of robustness decreases (good) as t increases.

2 Regression Prediction of US Inflation Data

§ **Source:** Yakov Ben-Haim, 2010, *Info-Gap Economics: An Operational Introduction*, Palgrave-Macmillan, section 6.1.

2.1 Data

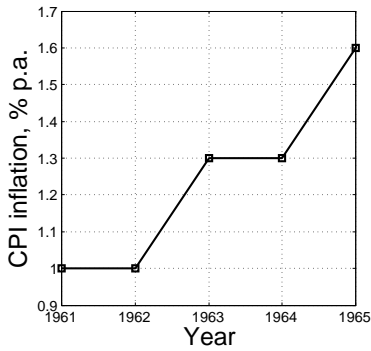


Figure 7: US inflation vs. year, 1961–1965.

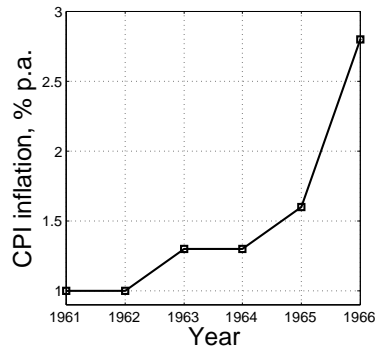


Figure 8: US inflation vs. year, 1961–1966.

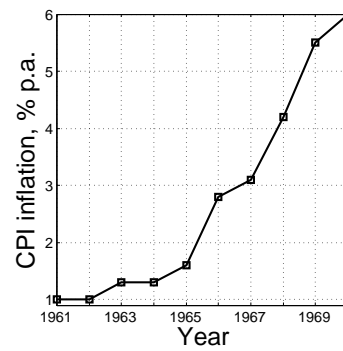


Figure 9: US inflation vs. year, 1961–1970.

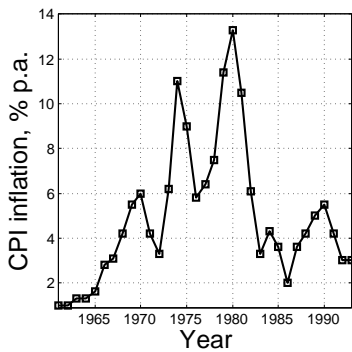


Figure 10: US inflation vs. year, 1961–1993.

§ US inflation:

- '61–'65: Linear?
- '61–'66: Quadratic?
- '61–'70: Piece-wise linear?
- '61–'93: A mess?

§ Modeling and predicting US inflation:

- '61–'65 Linear? Quadratic?
- Use the '61–'65 model for predicting '66:

$$y_i^r = c_0 + c_1 t_i + c_2 t_i^2 \tag{35}$$

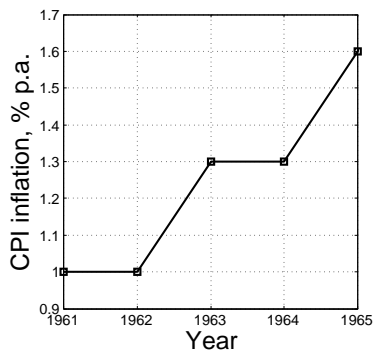


Figure 11: US inflation vs. year, 1961–1965.

2.2 System Model: Mean Squared Error

§ System model: Mean Squared Error (MSE).

For any vector of coefficients, c , the MSE is:

$$S_N^2(c) = \frac{1}{N} \sum_{i=1}^N (y_i - y_i^r)^2 \quad (36)$$

$N = 5$ for '61–'65. y_1, \dots, y_N are data. y_i^r is from eq.(35), p.8.

§ Least-squares estimate (LSE):

- Definition:

$$\tilde{c} = \arg \min_c S_N^2(c) \quad (37)$$

- Meaning: \tilde{c} is optimal estimate w.r.t. historical data.
- **Question:** Is \tilde{c} optimal wrt future data?
- LS regression: \tilde{c} in y_i^r from eq.(35), p.8:

$$\tilde{y}_i^r = \tilde{c}_0 + \tilde{c}_1 t_i + \tilde{c}_2 t_i^2 \quad (38)$$

- Calculation of LSE of coefficients:

$$\frac{\partial(S_N^2)}{\partial c_k} = 0, \quad k = 1, 2, 3 \quad (39)$$

3 linear equations in 3 unknowns.

- Does eq.(39) produce a minimum or maximum? Determinantal condition:

$$\left| \frac{\partial^2(S_N^2)}{\partial c_k \partial c_j} \right| > 0 \implies \text{minimum not maximum} \quad (40)$$

2.3 Uncertainty Model

§ Our knowledge:

- The data: y_1, \dots, y_N
- The LS estimate of the coefficients, \tilde{c} , and the corresponding quadratic function, \tilde{y}_i^r .
- **Contextual info:**
 - Under-prediction by \tilde{y}_i^r is very likely: y_{N+1} may well exceed the LS prediction, \tilde{y}_{N+1}^r .

◦ Over-prediction by \tilde{y}_i^r is very unlikely: y_{N+1} will not be less than the LS prediction, \tilde{y}_{N+1}^r .

§ **Info-gap model** of asymmetric uncertainty about LSE \tilde{y}_{N+1}^r :

$$\mathcal{U}(h) = \{y_{N+1} : 0 \leq y_{N+1} - \tilde{y}_{N+1}^r \leq h\}, \quad h \geq 0 \quad (41)$$

- Unbounded family of nested sets.
- No known worst case.
- Depends on the LS coefficients, \tilde{c} .

2.4 Robustness: Formulation and Derivation

§ **If we knew** y_{N+1} ('66):

$$S_{N+1}^2(c) = \frac{1}{N+1} \sum_{i=1}^{N+1} (y_i - y_i^r)^2 \quad (42)$$

$$= \frac{N}{N+1} S_N^2(c) + \frac{(y_{N+1} - y_{N+1}^r)^2}{N+1} \quad (43)$$

§ **Performance requirement.** For any coefficient vector, c , we require:

$$S_{N+1}(c) \leq S_c \quad (44)$$

§ **Robustness of regression** c : Greatest tolerable uncertainty.

$$\hat{h}(c, S_c) = \max \left\{ h : \left(\max_{y_{N+1} \in \mathcal{U}(h)} S_{N+1}(c) \right) \leq S_c \right\} \quad (45)$$

§ $m(h)$ is inner maximum in eq.(45):

- Inverse of $\hat{h}(S_c)$.
- From S_{N+1} in eq.(43): $m(h)$ occurs when y_{N+1} equals an extreme value at horizon of uncertainty h : either \tilde{y}_{N+1}^r or $\tilde{y}_{N+1}^r + h$:

$$m_1(h) = \sqrt{\frac{N}{N+1} S_N^2 + \frac{(\tilde{y}_{N+1}^r - y_{N+1}^r)^2}{N+1}} \quad (46)$$

$$m_2(h) = \sqrt{\frac{N}{N+1} S_N^2 + \frac{(\tilde{y}_{N+1}^r + h - y_{N+1}^r)^2}{N+1}} \quad (47)$$

- $m(h)$ is the greater of these two expressions:

$$m(h) = \max [m_1(h), m_2(h)] \quad (48)$$

- Recall our economic understanding: actual inflation, y_{N+1} , will exceed the LSE value, \tilde{y}_{N+1}^r .
- Hence only consider regressions y_i^r for which:

$$\tilde{y}_{N+1}^r \leq y_{N+1}^r \quad (49)$$

- Hence eq.(48) becomes:

$$m(h) = \begin{cases} \sqrt{\frac{N}{N+1} S_N^2 + \frac{(\tilde{y}_{N+1}^r - y_{N+1}^r)^2}{N+1}} & \text{if } h < 2(y_{N+1}^r - \tilde{y}_{N+1}^r) \\ \sqrt{\frac{N}{N+1} S_N^2 + \frac{(\tilde{y}_{N+1}^r + h - y_{N+1}^r)^2}{N+1}} & \text{if } h \geq 2(y_{N+1}^r - \tilde{y}_{N+1}^r) \end{cases} \quad (50)$$

- Thus $m(h)$ may switch between the two functions and display discontinuity of slope.
- Recall: $m(h)$ is the inverse of the robustness function.

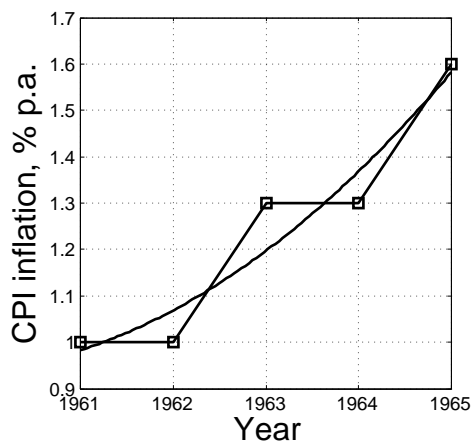


Figure 12: US inflation vs. year, 1961–1965, and least squares fit.

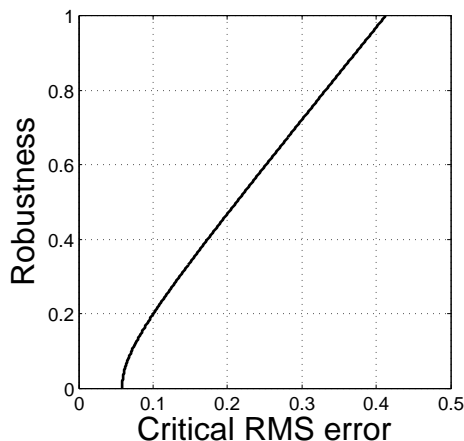


Figure 13: Robustness vs. critical root mean squared error for inflation 1961–1965.

2.5 Robustness: Results

§ **Least squares fit:** fig. 12: Maximal fidelity of quadratic function to the data.

§ **Robust of LS fit:** fig. 13.

- Trade off: Greater rbs. \equiv greater critical RMS error, S_c .
- Zeroing: No robustness of estimated RMS error, S_c .
- What do the numbers mean?

- $\hat{h} = 0.2$ at $S_c = 0.1$:

\hat{y}_{iN+1}^r can err by as much as 0.2 (from info-gap model, eq.(41), p.10)

if we require that

S_{N+1}^2 can err by no more than 0.1 (from performance requirement, eq.(44), p.10).

- $\hat{h} = 0.7$ at $S_c = 0.3$:

\hat{y}_{iN+1}^r can err by as much as 0.7 (from info-gap model, eq.(41), p.10)

if we require that

S_{N+1}^2 can err by no more than 0.3 (from performance requirement, eq.(44), p.10).

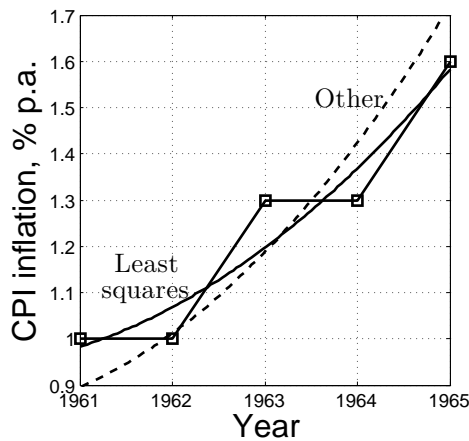


Figure 14: US inflation vs. year, 1961–1965, and least squares fit (solid) and other fit (dash).

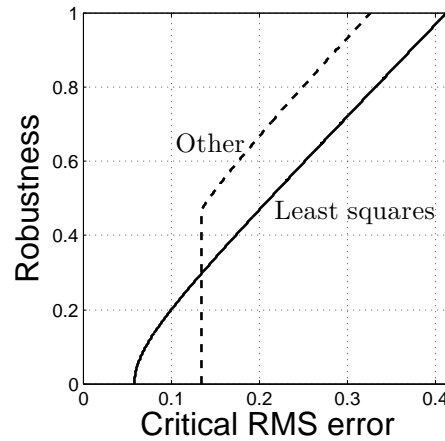


Figure 15: Robustness vs. critical root mean squared error for inflation 1961–1965 for least squares fit (solid) and other fit (dash).

§ Least squares and other fit: fig. 14.

- LS fit: Maximal average fidelity of quadratic function to the data.
- Other fit. Biased fidelity:
 - Under-estimate, on average, of early data. **Note:** 1962 is almost exact!
 - Over-estimate, on average, of late data.
 - Over-estimate of future wrt historical trend. **Maybe** 1966 will be exact!

§ Robust of LS and other fit: fig. 15.

- Zeroing: “Other” zeros at greater S_c : it’s nominal MSE is worse.
- Trade off: Both curves. ‘Other’ has greater (infinite) slope at zeroing value: lower cost of robustness.
- Curve-crossing: **preference reversal**.
- What do the numbers mean?
 - At $S_c = 0.1$:
 - $\hat{h}_{\text{other}} = 0$. $\hat{h}_{\text{LS}} = 0.2$. Forecast y_{N+1} with $\tilde{y}_{N+1}^r(\tilde{c})$ if $S_c = 0.1$ is adequate (or required).
 - At $S_c = 0.3$:
 - $\hat{h}_{\text{other}} = 0.8$. $\hat{h}_{\text{LS}} = 0.6$. Forecast y_{N+1} with $y_{N+1}^r(c)$ if $S_c = 0.3$ is adequate (or required).
 - Curve-crossing: **preference reversal**.
 - **Why** forecast y_{N+1} with $y_{N+1}^r(c)$ rather than with $\tilde{y}_{N+1}^r(\tilde{c})$?
 - Fidelity to data and forecast is our measure of performance of a forecaster, eq.(44), p.10.
 - $y_{N+1}^r(c)$ gives adequate fidelity ($S_c = 0.3$) over wider range of uncertainty than $\tilde{y}_{N+1}^r(\tilde{c})$.

3 Auto-Regression and Data Revision

§ **Source:** Yakov Ben-Haim, 2010, *Info-Gap Economics: An Operational Introduction*, Palgrave-Macmillan, section 6.2.

3.1 The Problem of Data Revision

§ **National statistical bureaus revise economic data over time.**

- **1974:**

- Real US GNP initially thought to have dropped 9.1% at annual rate between 3rd and 4th quarters.
- Largest drop since great depression.
- Final estimate, 20 years later: real GNP dropped 1.9% at annual rate.
- Not all revisions are this large.
- This revision large because of great economic turbulence then.
- Precisely in times of economic uncertainty we need accurate data.

- **2007–2009:**

- Typical revisions of 1 or 2 percentage points.
- Table 2.

	7q1	7q2	7q3	7q4	8q1
current	1.2	3.2	3.6	2.1	−0.7
previous	0.1	4.8	4.8	−0.2	0.9
	8q2	8q3	8q4	9q1	9q2
current	1.5	−2.7	−5.4	−6.4	−1.0
previous	2.8	−0.5	−6.3	−5.5	

Table 2: Current and previous estimates of real GDP: percent change from preceding period. 2007q1 to 2009q2. Seasonally adjusted at annual rates. Bureau of Economic Analysis, July 31, 2009.

3.2 Autoregression

§ **N scalar data points:** $y = (y_1, \dots, y_N)^T$.

E.g. inflation data over N sequential years as in fig. 7 on p.8.

§ **Regression:**

Choose coefficients $c = (c_1, \dots, c_J)^T$ of an auto-regression of order J for these data:

$$y_n = \sum_{j=1}^J c_j y_{n-j} \quad (51)$$

$$= c^T y_{n-1, n-J} \quad (52)$$

where $y_{n-1, n-J} = (y_{n-1}, \dots, y_{n-J})^T$.

§ **Define mean squared error of the auto-regression (AR) of the data:**

$$S^2(c) = \frac{1}{N-J} \sum_{n=J+1}^N (y_n - c^T y_{n-1, n-J})^2 \quad (53)$$

§ Our **system model** is the RMS error, $S(c)$.

§ **Performance requirement:**

$$S(c) \leq S_c \quad (54)$$

§ **The mean squared error can be expressed more compactly as:**

$$S^2(c) = \frac{1}{N-J} y^T V y \quad (55)$$

where V is defined as follows.

- e_n denotes the n th standard basis vector in \mathfrak{R}^N : the column N -vector with a 1 in the n th location and 0's elsewhere.

- Now the mean squared error can be written:

$$S^2(c) = \frac{1}{N-J} \sum_{n=J+1}^N \left[e_n^T y - \sum_{j=1}^J c_j e_{n-j}^T y \right]^2 \quad (56)$$

$$= \frac{1}{N-J} \sum_{n=J+1}^N \left[\underbrace{\left(e_n^T - \sum_{j=1}^J c_j e_{n-j}^T \right)}_{\zeta_n^T} y \right]^2 \quad (57)$$

$$= \frac{1}{N-J} \sum_{n=J+1}^N y^T \zeta_n \zeta_n^T y \quad (58)$$

$$= \frac{1}{N-J} y^T \underbrace{\left(\sum_{n=J+1}^N \zeta_n \zeta_n^T \right)}_V y \quad (59)$$

$$= \frac{1}{N-J} y^T V y \quad (60)$$

This is eq.(55), with $N \times N$ matrix V from eq.(59) and N -vectors ζ_n from eq.(57).

- V depends on the regression coefficients c but not on the data.

§ The AR coefficients that **minimize the mean squared error** are found by solving:

$$\frac{\partial S^2}{\partial c} = 0 \quad (61)$$

- Differentiating eq.(53) and rearranging one finds:

$$\underbrace{\sum_{n=J+1}^N y_n y_{n-1, n-J}}_z = \underbrace{\left(\sum_{n=J+1}^N y_{n-1, n-J} y_{n-1, n-J}^T \right)}_Y c \quad (62)$$

which defines the J -vector z and the $J \times J$ matrix Y .

- The least squares (LS) auto-regression coefficients are:

$$\tilde{c} = Y^{-1} z \quad (63)$$

If the inverse matrix does not exist then a generalized inverse needs to be used.

3.3 Uncertainty Model and Robustness Function

§ **Best estimate of the data:** $\tilde{y} = (\tilde{y}_1, \dots, \tilde{y}_N)^T$.

E.g. \tilde{y} might be current estimates of percent change in real GDP shown in table 2, p.13.

§ **Info-gap model for asymmetric information:**

$$\mathcal{U}(h) = \{y : \tilde{y}_n - w_{n1}h \leq y_n \leq \tilde{y}_n + w_{n2}h, n = 1, \dots, N\}, \quad h \geq 0 \quad (64)$$

- Uncertainty weights, w_{n1} and w_{n2} , are non-negative.
- If \tilde{y}_n is certain, then $w_{n1} = 0 = w_{n2}$.
- If \tilde{y}_n is believed to be an **underestimate** then $w_{n1} = 0$ and $w_{n2} = 1$.
- If \tilde{y}_n is believed to be an **over estimate** then $w_{n1} = 1$ and $w_{n2} = 0$.
- If the uncertainty is **symmetric** then uncertainty weights $w_{n1} = w_{n2}$.

§ **Robustness function, definition:**

$$\hat{h}(c, S_c) = \max \left\{ h : \left(\max_{y \in \mathcal{U}(h)} S(c) \right) \leq S_c \right\} \quad (65)$$

3.4 Policy Exploration

§ **Example** is based on 2nd-order auto-regressions, so $J = 2$ in eq.(51), p.13.

We use the percent change in the US GDP for 2007q1–2009q2 in table 2, p.13.

3.4.1 Symmetric Uncertainty

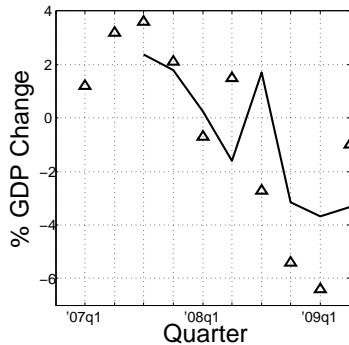


Figure 16: Current estimates of US real GDP change vs. quarter, and least squares auto-regression.

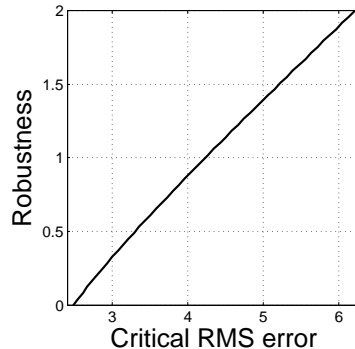


Figure 17: Robustness vs. critical RMS error of least squares auto-regression. Symmetric uncertainty.

§ **The data.**

- Fig. 16: GDP data, table 2, p.13, and 2nd-order least-squares auto-regression, \tilde{c} from eq.(63).
- LS regression coefficients are $\tilde{c} = (0.9139, -0.4647)^T$.
- The RMS error of this regression is $S(\tilde{c}) = 2.49$, so the AR misses the data, on average, by about 2.5 percentage points of GDP.
- This rather large error occurs mostly in last 5 quarters: data at '08q2 and '09q2 deviate from trend.
- Great uncertainty; no information on direction or magnitude of data revision.

- Use info-gap model of eq.(64) with $w_{n1} = w_{n2} = 1$ for $n = 1, \dots, N$.

§ **Robustness curve for LS AR \tilde{c} with symmetric uncertainty**, fig. 17.

- Zeroing at $S(\tilde{c}) = 2.49$.
- Trade off.
- $\hat{h}(S_c = 4) = 0.88$: RMS error no larger than 4% is guaranteed with robustness of 0.88: revisions as large as 0.88 percentage points can occur and the RMS error will not exceed 4%.

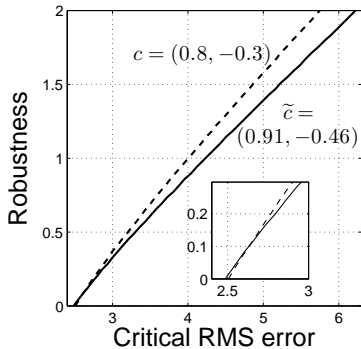


Figure 18: Robustness vs. critical RMS error with least squares (solid) and other (dash) auto-regression. Symmetric uncertainty.

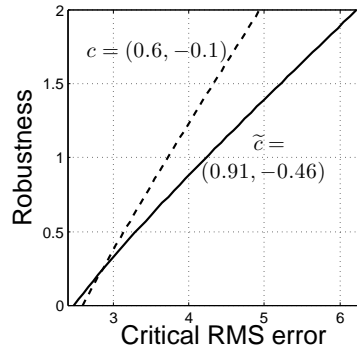


Figure 19: Robustness vs. critical RMS error with least squares (solid) and other (dash) auto-regression. Symmetric uncertainty.

§ **Robustness curves for non-LS AR with symmetric uncertainty**, figs. 18 and 19.

- LS robustness curve (solid) reproduced from fig. 17.
- LS robustness curve zeros to left of non-LS by definition of **least** squares.
- Non-LS robustness curves steeper: lower cost of robustness.
- Curve crossing and preference reversal.
- Two foci of uncertainty:
 - Statistical: seek small RMS.
 - Info-gap: seek large robustness.

3.4.2 Asymmetric Uncertainty

§ **Uncertainty and contextual information:**

- Data in fig. 16, p.15.
- Current estimates at 2008q2 and 2009q2 are over-estimates and will be revised down.
- Use info-gap model of eq.(64). Choose uncertainty weights:
 - $w_{6,2} = w_{10,2} = 0$: 6th and 10th estimates **cannot go up**.
 - $w_{6,1} = w_{10,1} = 1$: 6th and 10th estimates **can go down**.
 - $w_{nj} = 1$ for all other n and j (all other estimates can go either up or down).
- In summary:

$$w_2 = [1 \ 1 \ 1 \ 1 \ 1 \ 0 \ 1 \ 1 \ 1 \ 0] \tag{66}$$

$$w_1 = [1 \ 1 \ 1 \ 1 \ 1 \ 1 \ 1 \ 1 \ 1 \ 1] \tag{67}$$

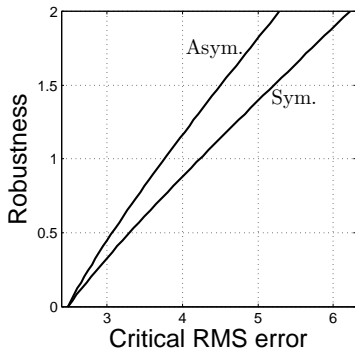


Figure 20: Robustness vs. critical RMS error for least squares regression with symmetric and asymmetric uncertainty.

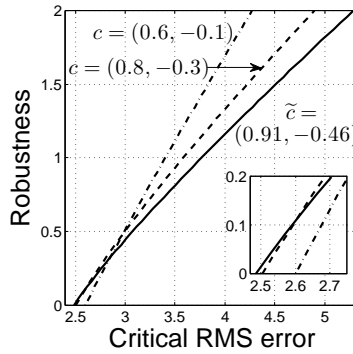


Figure 21: Robustness vs. critical RMS error with least squares (solid) and other (dash, dot-dash) regressions. Asymmetric uncertainty.

§ **LS auto-regression**, fig. 20:

- \tilde{c} does not depend on the info-gap model, so \tilde{c} is the same as before: $\tilde{c} = (0.9139, -0.4647)^T$.
- Furthermore, the RMS error of the LS regression same as before: $S(\tilde{c}) = 2.49$.
- However, the robustness of \tilde{c} *does* depend on the info-gap model, fig. 20.
 - Zeroing: both curves reach S_c axis at $S(\tilde{c})$.
 - Asymmetric robustness curve higher due to greater info in asymmetric info-gap model.

§ **Non-LS auto-regression**, fig. 21:

- Solid curve is LS regression: the “Asym.” curve from fig. 20.
- Curve-crossing with non-LS regressions.
- Large robustness gain by the non-LS over LS regressions.
- Compare with figs. 18 and 19:
 - Robustness gain is greater in current case.
 - Added asymmetric information enhances robustness of LS regression.
 - Further enhances the robustness of these non-LS regressions.